**How to use ML Framework**

**(v5.36)**

**What’s new in v5.36:**

* **EnvironmentType simplified**
* **It was transformed into InteractionType**
* **Now for more environments, is necessary a copy of the agent model inside the environment but no name change needed (instead a tag is used)**
* **SHORT TUTORIAL**
* Create the **AI** and add ***Agent.cs*** component. **Override** the Script. Create a new **AI Layer** that doesn’t interact with itself and a specific tag and apply both to the agent model. **Run** the simulation, **set a brain** and press **SaveBrain** (check the brain in /Neural\_Networks/), then **stop**.
* Create a **Trainer** GameObject and add ***Trainer.cs*** component. [Override the Script]. **Add the AI** Model. **Add the path** of the brain. [Choose the **training environment Type** and add the ***Environment*** **tag** to it.] [Add TMP\_text and Rect for statistics.] **Setup the training** settings. **Run the training**, the brain model is overwritten.
* Place the trained brain path to the AI and set behaviour to **Self**.
* **IN-DEPTH TUTORIAL**
* Download the .zip file from GitHub. Select the folder with the latest stable version.
* In the selected folder, you have access to three C# scripts. Upload all in your Scripts folder inside your Unity project.
* Create the following GameObjects :
* Your own AI agent [prefab] (+specific layer and tag) and add *Agent.cs* as component.
* One empty GameObject [called Trainer] and *Trainer.cs* add as component.
* [Optional but recommended for training performance] One or more empty GameObjects. Add for each one ***Environment*** tag. [When dealing with more environments, insert in each environment a copy of the agent (consider the agent has a specific tag)**,** this way the trainer will now know how to reset agents positions for each different environment]
* [Optional] A canvas with RenderMode on Screen Space – Camera (and drag your main camera in Render Camera), followed by the following objects:
* One TMP text (used for real time statistics)
* One RectTransform (used for evolution performance graph and neural net visualization)
* Override *Agent.cs* Script:
* Override **Heuristic()** and **OnActionReceived()**,and set behavior to *Manual* in order to test your AI behavior by keyboard. Override **CollectObservations()** and set Behavior to Heuristic to train your AI by learning from your actions.

Tip: Always keep agent Behavior to Static. When training, the behavior is auto set to Self.

* Decide your AI’s observations number. Override **CollectObservations()** by fullfiling *SensorBuffer* argument with specific data. Use *AddObservation(*) method to add different kind of observations. \*Note: every observation might have different size depending on how many float values are inside them*. Example: You decided to have 14 input values, you can add a Transform observation (where observation size is 10, 3 for position, 3 for localScale, 4 for rotation) ,a Vector3 observation (where observation size is 3, 1 for x, 1 for y and 1 for z) ,and an int value observation (where observation size is 1) . 10 + 3 + 1 = 14 input values. Do not let any gaps or inputs empty.*
* Decide your AI’s actions. Override **OnActionReceived()** by assigning actions depeding

on values received from *ActionBuffer*.You can access each action individualy by using *GetAction()* method and specify the index of the action. (outputs are in a range depending on the output activation function, usually (-1,1) if you use tanh, same as above, this method is called in Update(), use Time.deltaTime if needed)

* Create a Rewarding System. Use *AddReward()* or *SetReward()* to deprive or grant your agents performance.\*TIP: divide the reward by *episodesPerEvolution* to normalize the fitness (in case you want to train your agents on different environments/on more episodes, the average fitness will be counted this way). Use *EndAction()* to stop your agents from doing action. (use these methods in OnCollisionEnter/OnTriggerEnter when your AI touches a goal or a trap)
* Use or create variables like speed, rb, etc. under ***===AI Properties===*** header.

Note: Update and Awake are used in *AgentBase*. Update and Awake are virtual, if you need to use them, override them and call their bases.

* Create a brain model:
* Go back in UnityEditor and **Play**. Select your agent and take a look on *Agent (Script)* Component. Set *SpaceSize* by agent’s observations number and *ActionSize* by agent’s action number (as decided in the previous step). Modify *HiddenLayers* depending on your preference regarding on the NeuralNetwork structure. (biases are not included\*)
* Press *SaveBrain* checkbox once (don’t worry if it doesn’t modify to check sign) and press

**Stop**.

* Look in Assets\StreamingAssets\Neural\_Networks folder. There was created a .txt file with a brain model assigned with randomized weights. Right click on the file and select CopyPath.
* Set your Trainer (for Reinforcement training):
* Drag and drop your prefab/agentInHierarchy in *AI Model*.
* Paste Path copy in *BrainModelPath*.
* [Optional] Specify an Environment Type. The type is used to reset the scene objects’s and agent’s position/rotation/scale after each Episode.
* [Optional] Drag and drop TMP GameObject from Canvas in *Labels*. (don’t forget to adjust the text area – best on left half of the screen)
* [Optional] Drag and drop RectTransform [from Canvas] in *Graph*. (don’t forget to adjust the rectangle area and turn on Gizmos in Scene editor to watch the graph. The Neural Network represents the brain of the best AI in the scene, with the neurons colored in its color, biases in green, positive weights in blue and negative ones in red) \*adjust Canvas plane Distance accordingly when in a 3D project
* Set *=== Training Settings ===* at your preference. In the beginning, let Training Strategies on their default states.
* [Optional] Override Trainer.cs Script:
* Add Environment movement by overriding *EnvironmentAction()*
* Override *OnEpisodeBegin()* if needed.
* Override *OnEpisodeEnd()* if needed. (this method is called for each individual AI)
* Awake(), *Start()* and *SetupTeam()* are virtual**, *call base*** if you need to use them.
* Run the simulation:
* Since is a mono-environmental training, create a new layer that doesn’t intersect with itself and assign it to your AI (Edit -> Project Settings -> Physics[2D] -> Layer Collision Matrix) The AI’s will start training from their model starting position.
* Depending of what kind of training you want to simulate, turn on or off the Trainer. *See below how to process* ***Heuristic Training****.*
* Press **Play**.
* Check console to see the results of each generation.
* Enter in SceneEditor with Gizmos ON to watch the graph.
* Best AI’s brain is always overwritten over the .txt file placed in Trainer as path.
* Use the NeuralNetwork post-training:
* In **Agent.cs**, delete any [*AddReward*(), *SetReward*() or] *EndAction*() calls.
* Copy the path of the brain model and paste inside *Path* (from *=== Network Properties ===*).
* Set Behavior to *Self*.
* Your AI’s is now ready.
* **INTERACTION TYPES**
* Use *Not Specified* if not needed.
* Add tag **Environment** for all your environments you want to use (at least 1).
* Add a copy of your agent in each environment and change it’s name to **Start**. Adjust it’s the position and rotation (even of it’s children).
* **More Agents Per Environment**: In this situation, the agents are trained togheter in the same environment by overlapping each other. When there is more than 1 environment, is necessary for each of them to have a model of the agent inside (representing the starting position), otherwise the main model is used as a start.
* **One Agent Per Environment**: This is mainly used when you need to let just 1 agent to interact with the environment. To properly use this, take your normal environment and clone it for several times. When training, one agent is placed inside each of them. (team size is adjusted automatically to the number of environment clones).
* **\*Whenever you want to not use an environment, remove it’s tag.**
* **TRAINER IN DEPTH**
* Use a small number of hidden layers (even 0), the training process will be faster.
* **Save Brains:** When you see an AI that has good behavior and doesn’t manage to get too much fitness, *Save Brains* from Trainer or *Save Brain* from Agent, stop the training and use his brain for another training session.
* **TeamSize:** Use as much AI’s as possible while keeping the framerate stable (around 60)
* **Episodes per Evolution:** Let more episodes to train for one generation. Rewarding is cumulative. The next generation occur every ***x***episodes.
* **Maximum Episode Time:** Give a limited time to your AI’s per Episode. \**Because some AI’s might never end their action the episode will run forever.*
* **Training Strategy Switch:** At the beginning of training, start with *Strategy 1*. When you see an AI that is quite good since his behavior is close to what you expect and he managed a good fitness, switch to *Strategy 2* (this way the best brain will be inserted in 1/3 of the AI’s and mutated every Episode). If your AI is ready you can go for a training with Strategy 3, where only the best brain is reproduced, this might be good to find a better AI with the same behavior.
* **Mutation Strategy Switch:** Use Classic *MutationStrategy* mostly. You might switch to Light/Strong Percentage in combination with *Strategy 3* to fine-tune your agent abilities.
* **Agent’s network activation Type Switch:** You can play with any of these functions. *\*Output activation function will affect your output values range. Tanh returns values in range (-1,1), BinaryStep returns binary values, Sigmoid returns values in range (0,1), ReLU returns values In range [0, +infinity) and SiLU returns same values as ReLU but in a smooth manner.*
* **Agent’s network initialization Type Switch:** The switch will not make a significant change, is more like a flavor for weights and biases initialization.
* **HEURISTIC TRAINING**
* Load a path to a brain. Turn OFF the *Trainer*. Set behavior to Heuristic. Set module to **Append/Write** (it will write the training data in a file). Start your simulation and control your agent consistently. **Do not** **stop** the simulation until the data was stored. After this, go to the newly created Directory *Heuristic\_Samples* and copy the path of the file to **Samples Path**. Set the Module to **Learn**. Run the simulation again, this time deep learning is processed using the data inside the file. Do not stop until is finished.
* **Samples Path** is the path of the file where training data is stored or used. It is auto created if doesn’t exist when appending/writing.
* **Module** represents the interaction mode. If is set to **Append** or **Write**, the user gives training data through the keyboard or mouse, data is stored in a txt file in Heuristic\_Samples. If is set to **Learn**, the machine reads the data from the *Samples\_Path* and trains. \*Note: do not append more than 1 milion samples in just 1 file, the machine will work extremely slow when training.
* **Epochs** are the number of times the data is reprocessed. A high number of Epochs may cause overfitting, a low number may cause underfitting. \*\*\****Reducing the number of epochs while training is the only way to stop safely the simulation.***
* **Session Length** represents the time you spent on giving data to the training file. Longer the session, more divert the data will be.
* **LearnRate** can be modified depeding on the learn impact for your agent. Keeping it too low may not cause major impact on the network itself, keeping it to high doesn’t show any beneficial results, and can even shatter the old parameters peformance. For example: if the learn rate is 0.01, for 1 epoch the impact is 1%. A good formula to follow:

Learn Rate = of impact you want% / number of epochs.

DevNote: the learnRate is divided by the batch\_size in HeuristicPreparation().

* **CostType** is the function used to calculate the total error of the outputs comparing to the user controls (desired outputs). Best keep on Quadratic.
* **CurrentError** shows the error between the network outputs and user outputs.

The heuristic training process must decrease this value as much as possible. When the *Current Error* is approaching to 0, you can end the Heuristic Training and pursue with the Trainer.

* **ErrorGraph** shows the progression of the error. To get the best results for your agent, watch the graph carefully. When the error reaches a minimum value and from there is starts rising slowly, finnish the training by changing the epoch from inspector to 0.
* **Environment** works in the same way, but don’t needs a specific tag, just drag and drop your Environment gameobject here to reset the environment every time the agent action ends. Supports only monoenvironment.
* Override **HeuristicOnSceneReset()** to modify the environment or agent position differently for each Scene.
* This type of training is good especially before the Trainer, to yield a good start for the agents. UnityEditor FPS will decrease dramatically ( to ~1 fps), that’s because all the resources are used only for the training.